

GRADIENT BASED RECONSTRUCTIONS FOR ADAPTIVE OPTICS SYSTEMS

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Introduction

Large ground-based telescopes rely on Adaptive Optics (AO) systems in order to achieve a good image quality. Due to steadily growing telesope sizes there is a strong increase in the computational load for atmospheric reconstruction with current methods, first and foremost the MVM.

Adaptive Optics system:

Input: Shack-Hartmann wavefront sensor (WFS) data of guide star α_g , g = 1,...,G on each sub-aperture Ω_{ij} of the aperture Ω_D $\Gamma: H^1(\Omega_D) \to \mathbb{R}^{2\#sub}, \ \#sub \dots$ number of active sub-apertures



Forward operators:
• LGS data:
$$\mathbf{A}_{\alpha_g} : \bigotimes_{l=1}^{L} L_2(\mathbf{\Omega}_l) \to L_2(\mathbf{\Omega}_D)$$
 with geometric light propagation [1]:
 $\mathbf{A}_{\alpha_g} \mathbf{\Phi} := \sum_{l=1}^{L} T^{\alpha_g h_l} \Phi^{(l)} = \varphi_{\alpha_g}(\mathbf{r})$, with $(T^{\alpha_g h_l} \Phi^{(l)})(\mathbf{r}) := \Phi^{(l)}(c_l \mathbf{r} + h_l \alpha_g)$, $\mathbf{r} \in \mathbf{\Omega}_D$.
 $\mathbf{\Phi} = (\Phi^{(1)}, \dots, \Phi^{(L)})^T$, ... turbulence layers, $c_l := 1 - \frac{h_l}{h_{LGS}}$, h_{LGS} ... LGS height.
 $\langle \mathbf{\Phi}, \mathbf{\Psi} \rangle := \sum_{l=1}^{L} \frac{1}{\gamma_l} \langle \Phi^{(l)}, \Psi^{(l)} \rangle_{L_2(\Omega_l)}$, $\gamma_l \dots c_n^2$ -profile of layer $l (\sum_{l=1}^{L} \gamma_l = 1)$
with the L_2 -adjoint: $\mathbf{A}_{\alpha_g}^* : L_2(\mathbf{\Omega}_D) \to \bigotimes_{l=1}^{L} L_2(\mathbf{\Omega}_l)$ where
 $\mathbf{A}_{\alpha_g}^*(\mathbf{\Psi}) = (\gamma_1(T^{\alpha_g h_1})^* \mathbf{\Psi}, \dots, \gamma_L(T^{\alpha_g h_L})^* \mathbf{\Psi})^T$, $(T^{\alpha_g h_l})^* \mathbf{\Psi} = \mathbf{\Psi}(\mathbf{r} - \alpha_g h_l) \chi_{\Omega_D(\alpha_g h_l)}(\mathbf{r})$
• Tip-tilt data [3]: $\mathbf{N}_{\beta_l} : \bigotimes_{l=1}^{L} H^1(\Omega_l) \to \mathbb{R}^2$, with
 $\mathbf{N}_{\beta_l} \mathbf{\Phi} = \mathbf{t}_{\beta_l} = \begin{pmatrix} t_{\beta_l}^x \\ t_{\beta_l}^y \end{pmatrix} \in \mathbb{R}^2$, $i = 1, \dots, N$, $\mathbf{r} = (x, y) \in \mathbf{\Omega}_D$ and
 $t_{\beta_l}^x = \sum_{l=1}^{L} \int_{\Omega} \frac{\partial}{\partial x} \Phi^{(l)}(\mathbf{r} + h_l \beta_l) d\mathbf{r}$, $t_{\beta_l}^y = \sum_{l=1}^{L} \int_{\Omega} \frac{\partial}{\partial y} \Phi^{(l)}(\mathbf{r} + h_l \beta_l) d\mathbf{r}$.



Output: DM commands Φ_{DM}

WFS sub-apertures

Instead of using one big matrix-vector system, one can decouple the problem in 3 steps:

3-step approach[1]:

Solve AO problem sequently:

1. Reconstruct incoming wavefronts from SH WFS data: $\varphi_{\alpha_g} = \text{CuReD}(s_{\alpha_g}^x, s_{\alpha_g}^y)$ [2]

2. Atmospheric tomography: Gradient-based method

3. Compute optimal mirror shapes from the reconstructed atmosphere (fitting step): projection of reconstructed atmosphere Φ onto DMs

 \Rightarrow flexible and fast reconstruction!

AO systems such as Multi Conjugate AO (MCAO), Laser Tomography AO (LTAO) or Multi Object AO (MOAO) all require atmospheric tomography but differ in the projection step. In the following, we propose a gradient based method for the atmospheric tomography. The main goal of this iterative approach is the comparability with the MVM method in quality and a considerable reduction of computational cost.

Problem modelling

Tip-tilt indetermination:

With natural guide stars (NGS) only a low sky coverage reached



Solve
$$\mathbf{A} \Phi = \varphi \Leftrightarrow \begin{pmatrix} \mathbf{A}_{\alpha_1} \\ \vdots \\ \mathbf{A}_{\alpha_G} \end{pmatrix} \Phi = \begin{pmatrix} \varphi_{\alpha_1} \\ \vdots \\ \varphi_{\alpha_G} \end{pmatrix} = \varphi \text{ with } \mathbf{A}^* = \sum_{g=1}^G \mathbf{A}_{\alpha_g}^* + \sum_{n=1}^N \mathbf{N}_{\beta_n}^*.$$

Least squares solution with penalty term (MAP estimation):

 $J(\mathbf{\Phi}) = \|\mathbf{A}\mathbf{\Phi} - \varphi\|_{\overline{C_{\eta}}^{-1}}^{2} + \alpha_{\Phi} \|\mathbf{\Phi}\|_{C_{\Phi}^{-1}}^{2} \to \min$ $J'(\mathbf{\Phi}) = -2\mathbf{A}^{*}\overline{C_{\eta}}^{-1}(\varphi - \mathbf{A}\mathbf{\Phi}) + 2\alpha_{\Phi}C_{\phi}^{-1}\mathbf{\Phi} =: -\mathbf{d}$

Steepest descent with stepsize τ :

$$\begin{split} \mathbf{\Phi}_{j+1} &= \mathbf{\Phi}_j + \tau_j \mathbf{d}_j \\ \tau_j &= \min_{t \in \mathbb{R}} J(\mathbf{\Phi}_j + t \mathbf{d}_j) \\ &= \frac{\sum_{l=1}^L \frac{1}{2} \langle \mathbf{d}_j^{(l)}, \mathbf{d}_j^{(l)} \rangle_{L^2(\Omega_l)}}{\langle \overline{C_\eta}^{-1} \mathbf{A} \mathbf{d}_j, \mathbf{A} \mathbf{d}_j \rangle_{L^2(\Omega_D)} + \alpha_\Phi \sum_{l=1}^L \langle (C_\Phi^{(l)})^{-1} \mathbf{d}_j^{(l)}, \mathbf{d}_j^{(l)} \rangle_{L^2(\Omega_l)}} \end{split}$$

well parallelizable method
easily adaptable to changes in asterism

• can also be used without noise statistics ($\overline{C_{\eta}} = I$, $\alpha_{\Phi} = 0$) e.g. for highflux, without spot elongation

 \rightarrow artificial laser guide stars (LGS) are created with laser beacons. Problem: average of derivatives of incoming wavefronts (tip-tilt) is wrong \rightarrow combine LGS and NGS.

SH WFS measurements from LGS are affected by spot elongation due to the non-zero thickness of the sodium layer. Depending on the laser launch position (the height of the LGS and the sodium layer) one can model the corresponding covariance matrix for the noise.

Spot elongation: For exact WFS data $s_{\alpha_g} = [s_{\alpha_g}^x s_{\alpha_g}^y]$ one can model the noisy measurements by: $s_{\alpha_g}^{\delta} = s_{\alpha_g} + C_{\alpha_g}^{1/2} \eta$, with η white noise. Thus, $\varphi_{\alpha_g}^{\delta} = \Gamma^{-1}(s_{\alpha_g} + C_{\alpha_g}^{1/2} \eta)$ and $\operatorname{cov}(\varphi_{\alpha_g}) = \Gamma^{-1}C_{\alpha_g}\Gamma^{-T}$ (with Γ the discretized SH operator). Therefore, $\operatorname{cov}(\varphi) = \Gamma^{-1}C_{\eta}\Gamma^{-T} =: \overline{C_{\eta}}$ with $C_{\eta} = \operatorname{diag}(C_{\alpha_1}, \ldots, C_{\alpha_G}).$

Statistics of the atmosphere:

To model the atmosphere, a finite number layers $l = 1, \ldots L$ is used. Each layer can be described e.g. by the Kolmogorov turbulence model with covariance matrices $C_{\Phi}^{(l)}$ and the c_n^2 -profile γ_l measuring the turbulence strength of layer l.

Atmospheric Tomography

Input:

Problem formulation:

without spot elongation

Quality results

All results below were obtained for the E-ELT on the ESO end-to-end simulator, OCTOPUS.

Multi Conjugate AO (MCAO):

- 6 LGS in a circle of radius 1 arcmin
- 3 TTS in a circle of radius 4/3 arcmin
- 3 DMs (0m, 4km, 12.7km)
- 3-layer reconstruction on DMs
 pseudo open loop control (polc)
 wo spot elongation → no noise models needed
 only few iterations needed



Computational complexity: n ~ 0.75 ⋅ 84² = 5292, with a 84x84 SH-WFS CuReD: 20 ⋅ n per guide star Gradient: ~ ((16L+2) ⋅ (G+N) + (L+2)) ⋅ n per iteration, e.g. 3 layers, 6 LGS, 3 NGS: ~ 455n

• calculation in guide star directions is parallelizable

Lowflux (100 photons per sub-aperture)

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• reconstructed incoming wavefronts φ_{α_g} from LGS $g = 1, \ldots, G$ on Ω_D (aperture)

- tip/tilt data $\mathbf{t}_{\beta_n} \in \mathbb{R}^2$ from natural guide stars $n = 1, \dots, N$ Goal:
- **fast** reconstruction of turbulence layers $\Phi^{(l)}$ on Ω_l , l = 1, ..., L
- \implies ill-posed inverse problem, requires regularization.

References

- [1] R. Ramlau and M. Rosensteiner: An efficient solution to the atmospheric turbulence tomography problem using Kaczmarz iteration. Inverse Problems, 28 (2012)
- M. Rosensteiner: Wavefront reconstruction for extremely large telescopes via CuRe with domain decomposition. J. Opt. Soc. Am. A, 11 (2012)
- [3] R. Ramlau, A. Obereder, M. Rosensteiner, D. Saxenhuber: *Efficient iterative tip/tilt reconstruction for atmospheric tomography*, submitted



Multi Object AO (MOAO)
6 LGS (3.75 arcmin)
3 NGS (5 arcmin)
1 ground DM, open loop
highflux, wo spot elongation

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